

IN THE SPECIFICATION

Please amend paragraph [0010] as follows:

[0010] In addition, as described below, the driving mechanism of the modular device and an optional viewing device, make it is possible to accurately position the modular device. The accuracy in positioning may reduce the time required for the treatment and may also reduce risk of erroneously treating the wrong area.

Please amend paragraph [0018] as follows:

[0018] FIG. 4 shows a further embodiment of a drive mechanism 112 provided in modular device 110. In this embodiment, ~~a~~ an electric motor 115 is provided inside modular device 110. The motor 115 may be powered as described above, and includes a rotor 132 and stator 134 arrangement, as would be understood by those of skill in the art. The rotor 132 is positioned within the stator portion 134 and includes a central threaded portion. Rotor 132 is positioned within the modular device 110 to engage and rotate about guide track 120b, which is embodied as a coiled guidewire or shaft. As shown in FIG. 4, the coils of the guide track 120b provide a substantially helical threaded surface which is engaged by the corresponding threaded portions 111a, 111b of the lumen extending through the modular device 110 through which the guide track 120b passes are formed at the proximal and distal ends of the modular device 110. Contact between these threaded portions 111a, 111b and the guide track 120b as the modular device 110 is rotated by the electric motor 115 moves the modular device proximally or distally therealong depending on the direction of rotation. Those skilled in the art will understand that the rotor 132 may optionally be nonrotatably coupled to the threaded portions 111a, 111b while a radially outer portion of the modular device 110 is rotatably coupled to the rotor 132 and the threaded portions 111a, 111b so that this radially outer portion may maintain a substantially constant angular orientation relative to the guide track 120b as the modular device 110 is moved therealong.